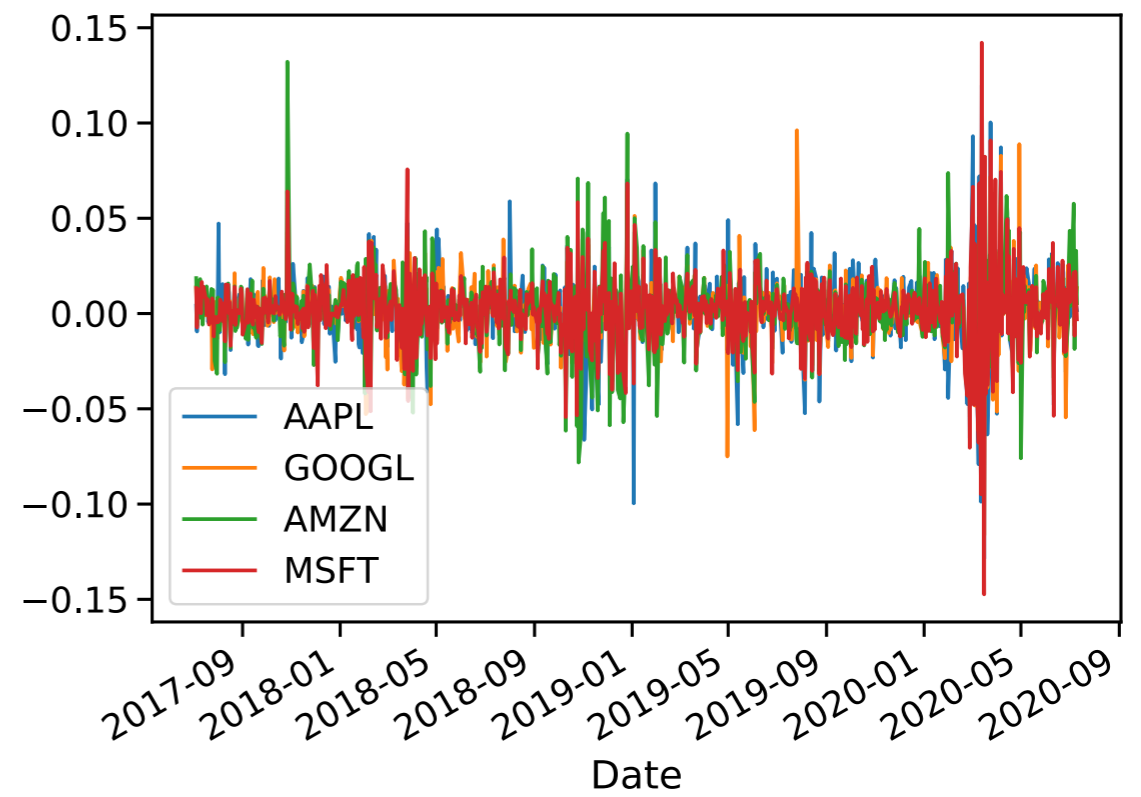
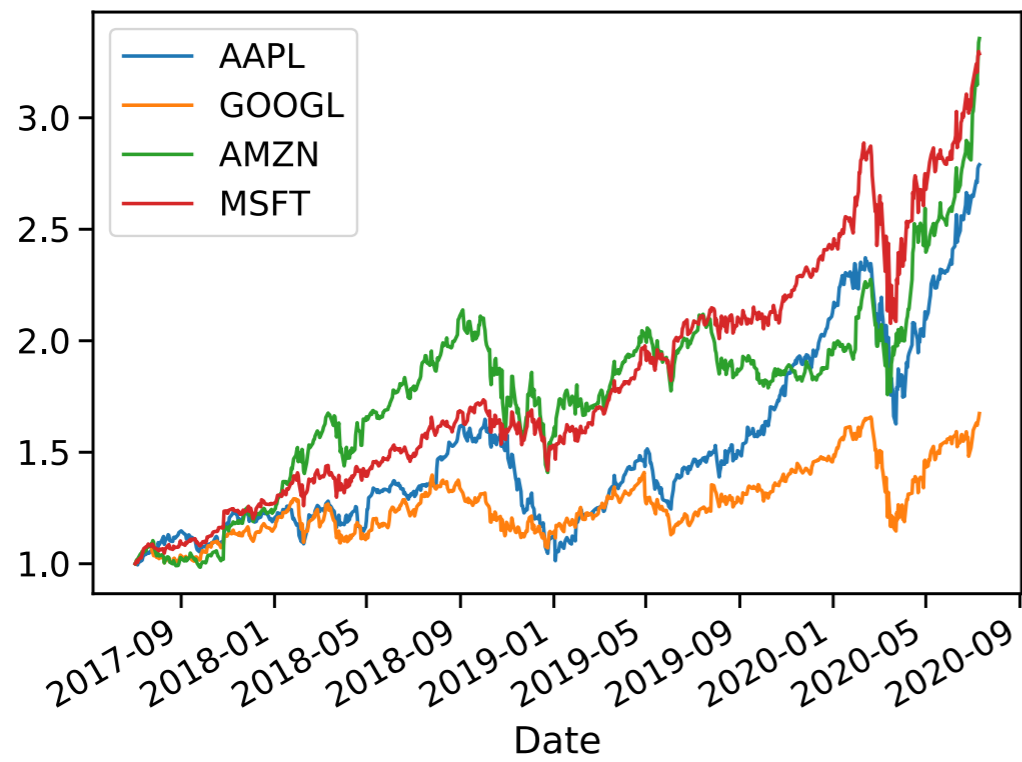
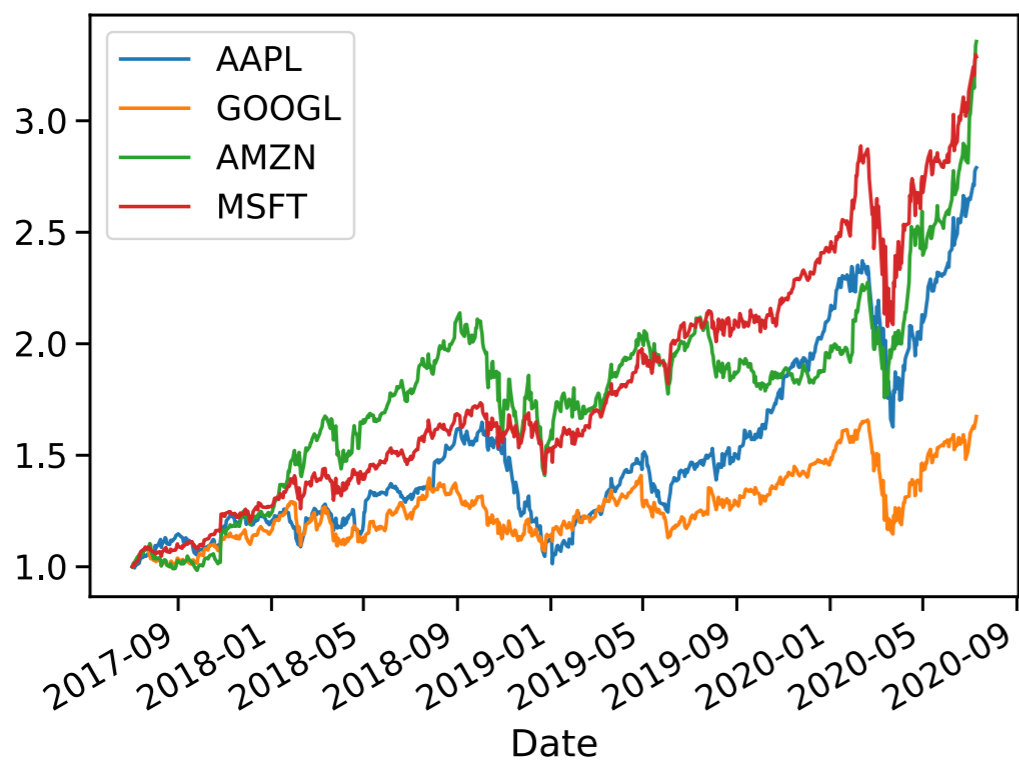


Gaussian Process Latent Variable Models in Finance

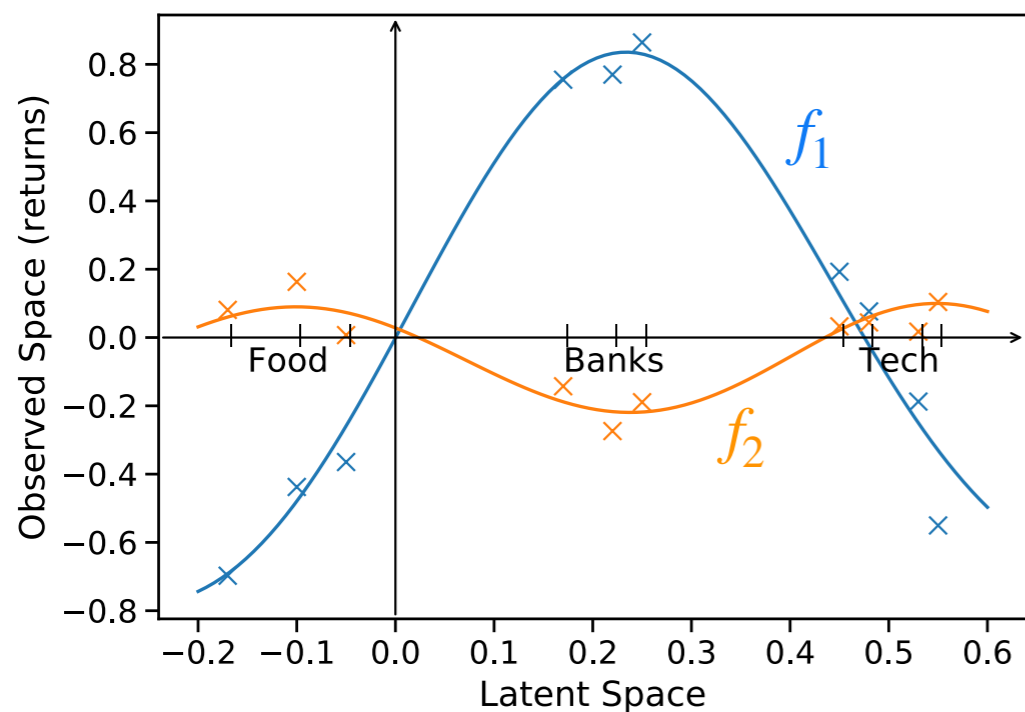
Rajbir-Singh Nirwan





RETURNS	07.07.20	08.07.20	09.07.20	10.07.20
AAPL	-0.31	2.33	0.43	0.17
GOOGL	-0.64	0.92	1.00	1.34
AMZN	-1.86	2.70	3.29	0.55
MSFT	-1.16	2.20	0.70	-0.30
FOOD				
BANK				

Generative Model



	Day1	Day2
Bank1	-0.70	0.08
Bank2	-0.44	0.16
Bank3	-0.36	0.01
Food1	0.75	-0.14
Food2	0.77	-0.27
Food3	0.86	-0.19
Tech1	0.19	0.03
Tech2	0.08	0.04
Tech3	-0.19	0.02
Tech4	-0.55	0.10

Outline

- Gaussian Processes
- Latent Variable Models
- Applications
 - Portfolio Allocation
 - Predicting missing Values
 - Structure Identification

Gaussian Processes

- Non-Parametric Kernel based approach
- Utilize full power of Bayesian statistics
- Complexity increases with the number of data points

Gaussian Processes

Weight space view

$$\Phi : x \rightarrow (\phi_1(x), \phi_2(x), \dots, \phi_D(x))$$

$$f(x) = \mathbf{w}^T \Phi(x)$$

Simple and easy to interpret
but limited flexibility

$$f(x) = \mathbf{W}_2 \sigma(\mathbf{W}_1 \Phi_1(x))$$

Highly flexible
but not interpretable

$$\phi(x) = x$$

$$k(x, x') = xx'$$

$$\Phi(x) = (x, x^2)$$

$$k(x, x') = xx' + x^2x'^2$$

Function space view

$$k : x, x' \rightarrow k(x, x')$$

Flexibility increases with
number of data points

Mercers Theorem:

$$k(x, x') = \sum_d \lambda_d \phi_d(x) \phi_d(x')$$

$$k(x, x') = (xx' + c)^d$$

$$\Phi(x) = \text{polynomials up to order } d$$

$$k(x, x') = \exp(-0.5 (x - x')^2 / \ell^2)$$

$$\Phi(x) = \text{infinitely many basis functions}$$

Gaussian Processes

Any finite collection of function values at x_1, x_2, \dots, x_N is jointly Gaussian distributed

$$p\left(f(x_1), f(x_2), \dots, f(x_N)\right) = \mathcal{N}(\boldsymbol{\mu}, \mathbf{K}) = \mathcal{N}\left(\begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} k_{11} & k_{12} & \cdots & k_{1N} \\ k_{21} & k_{22} & \cdots & k_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ k_{N1} & k_{N2} & \cdots & k_{NN} \end{pmatrix}\right) \quad k_{ij} = k(x_i, x_j)$$

Common Kernel Functions

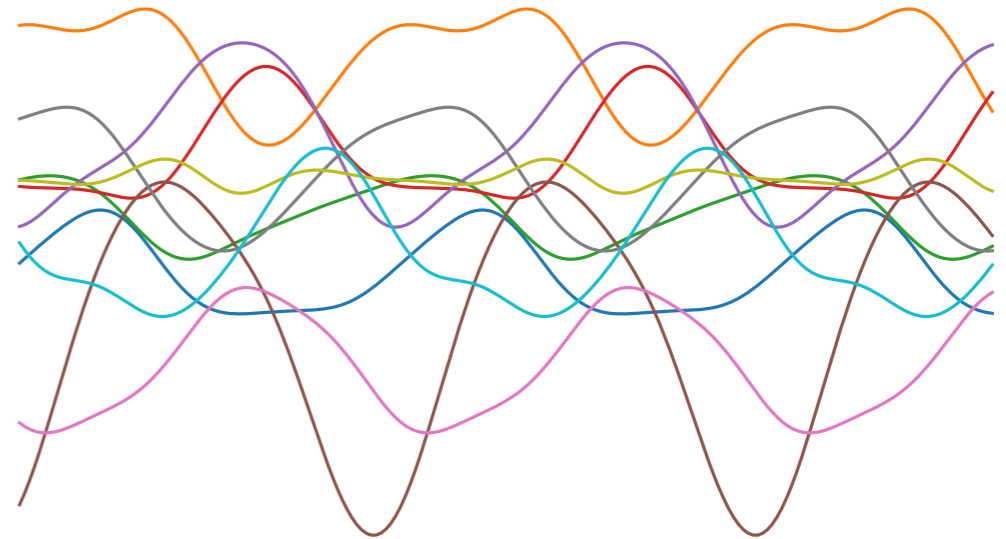
$$k_{linear}(x, x') = xx'$$

$$k_{rbf}(x, x') = \exp\left(-\frac{1}{2\ell^2}(x - x')^2\right)$$

$$k_{ou}(x, x') = \exp\left(-\frac{1}{\ell}|x - x'|\right)$$

$$k_{mat32}(x, x') = \left(1 + \frac{\sqrt{3}|x - x'|}{\ell}\right) \exp\left(-\frac{\sqrt{3}|x - x'|}{\ell}\right)$$

$$k_{periodic}(x, x') = \exp\left(-\frac{2}{\ell^2} \sin^2(|x - x'|)\right)$$

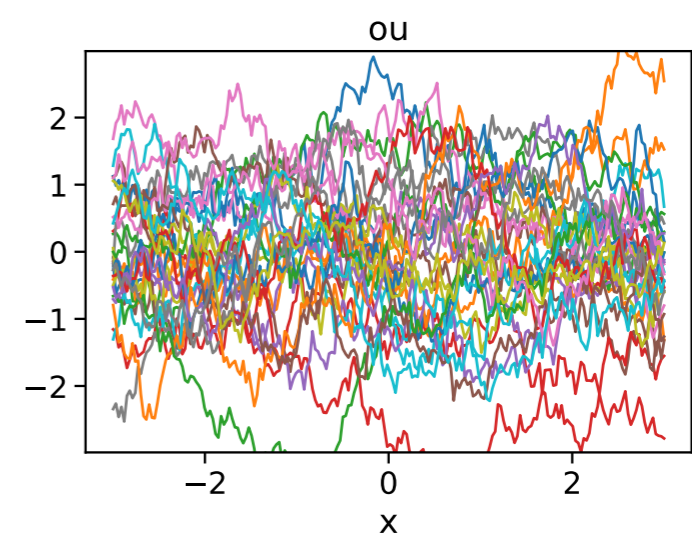
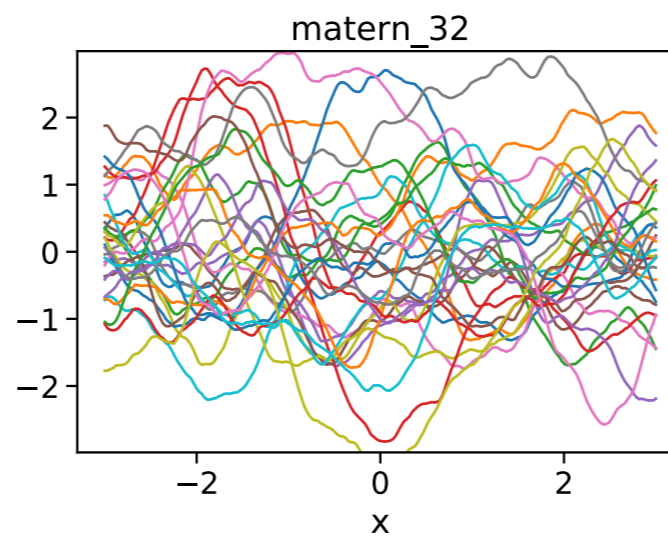
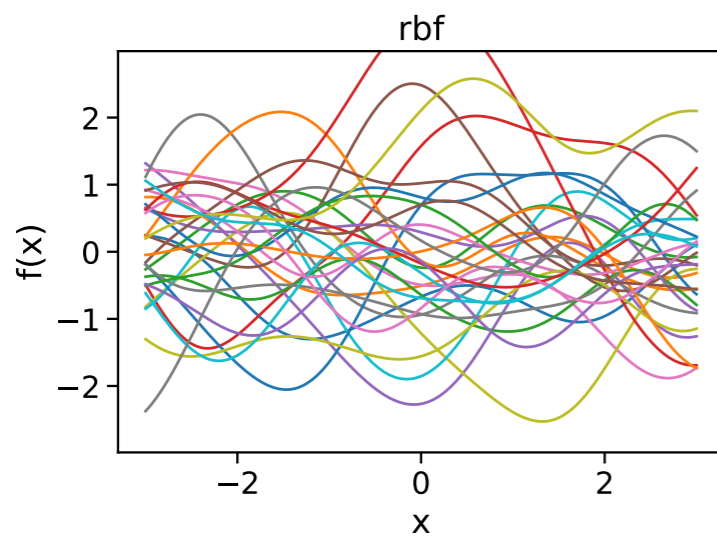


Gaussian Processes

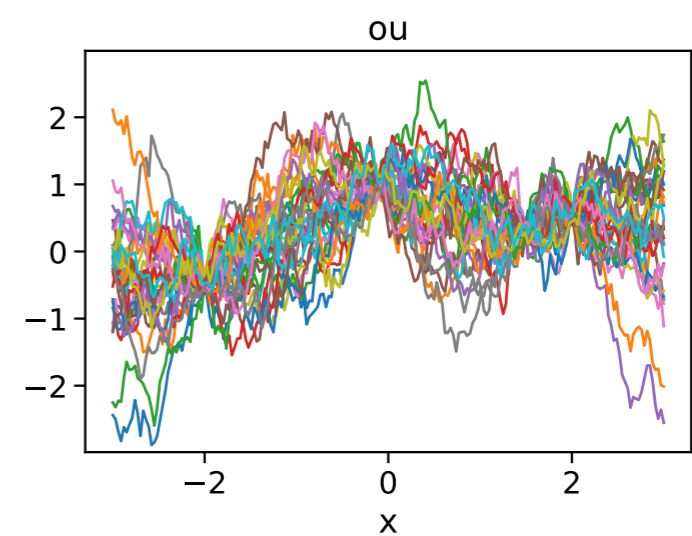
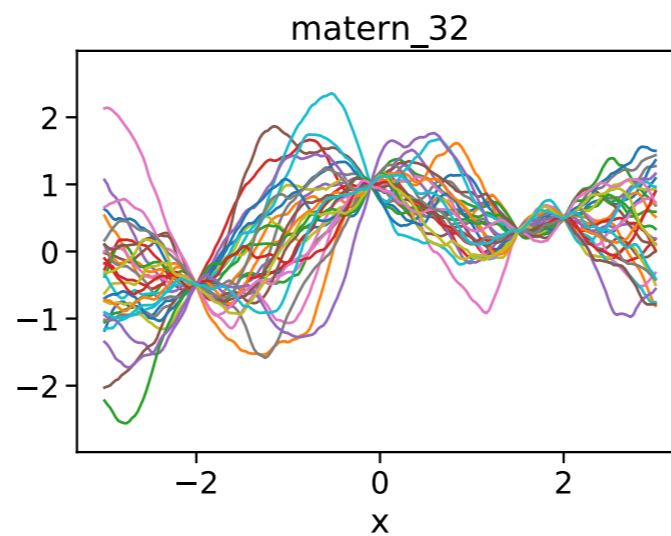
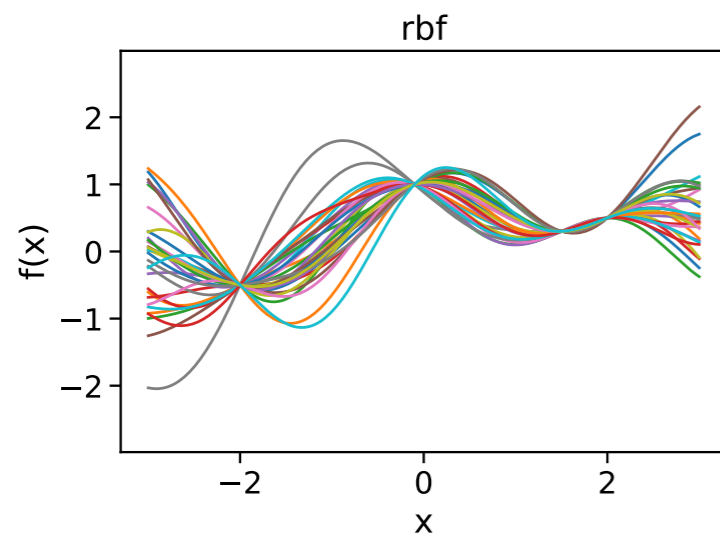
Bayes Theorem

$$p(f | \mathcal{D}) = \frac{p(\mathcal{D} | f)p(f)}{p(\mathcal{D})}$$

Prior

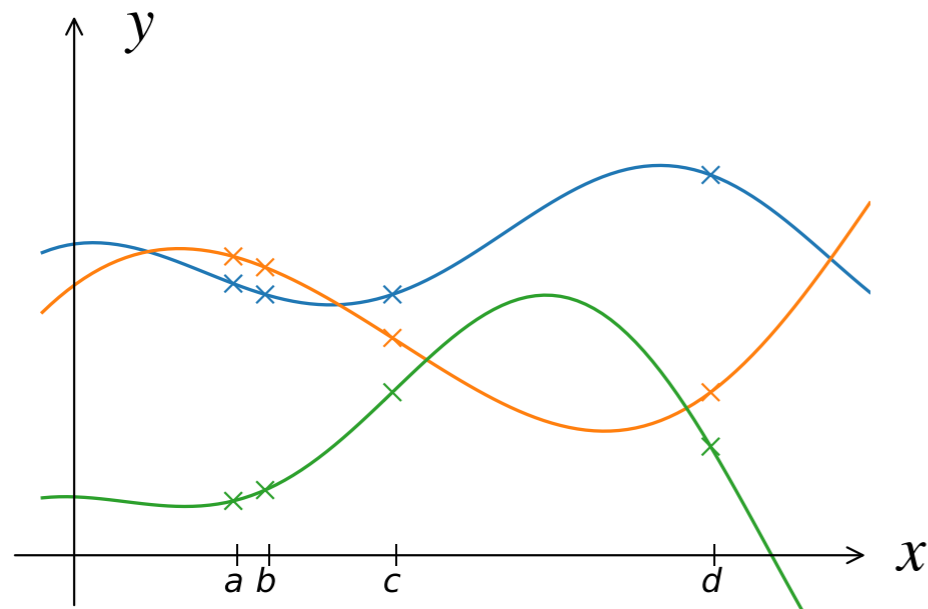


Posterior



Latent Variable Models

$$\mathbf{X} \in \mathbb{R}^{N \times Q} \xrightarrow{f} \mathbf{Y} \in \mathbb{R}^{N \times D}$$



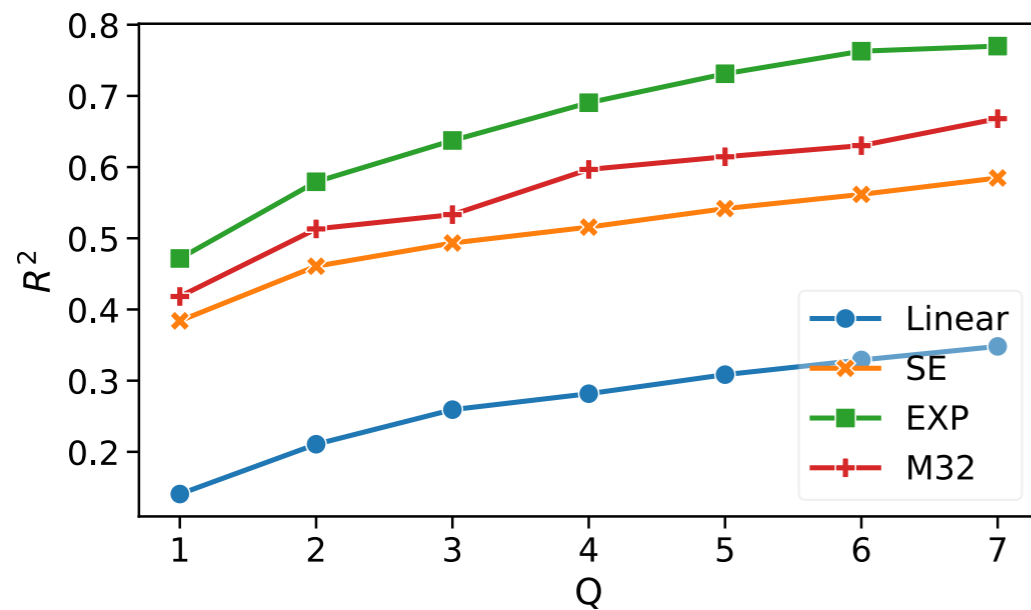
$$\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \xrightarrow{f_i} \begin{pmatrix} a_1 & a_2 & a_3 & \dots \\ b_1 & b_2 & b_3 & \dots \\ c_1 & c_2 & c_3 & \dots \\ d_1 & d_2 & d_3 & \dots \end{pmatrix}$$

- Can we infer the hidden state \mathbf{X} only by looking at \mathbf{Y} ? Yes
- Inference using GPs also gives us the covariance \mathbf{K} between different points

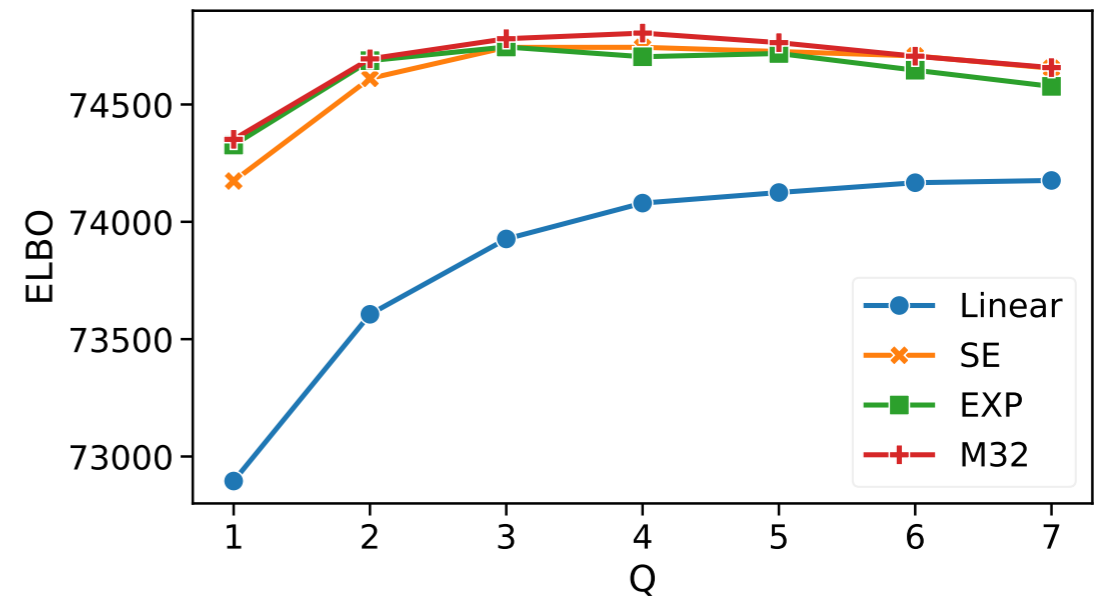
Experiments

Use **Variational Bayes** for the inference - data $Y \in \mathbb{R}^{N \times D}$
Approximate the true posterior with a simple distribution

R^2 - Variance of the data captured by the model



ELBO - Lower bound to the marginal likelihood



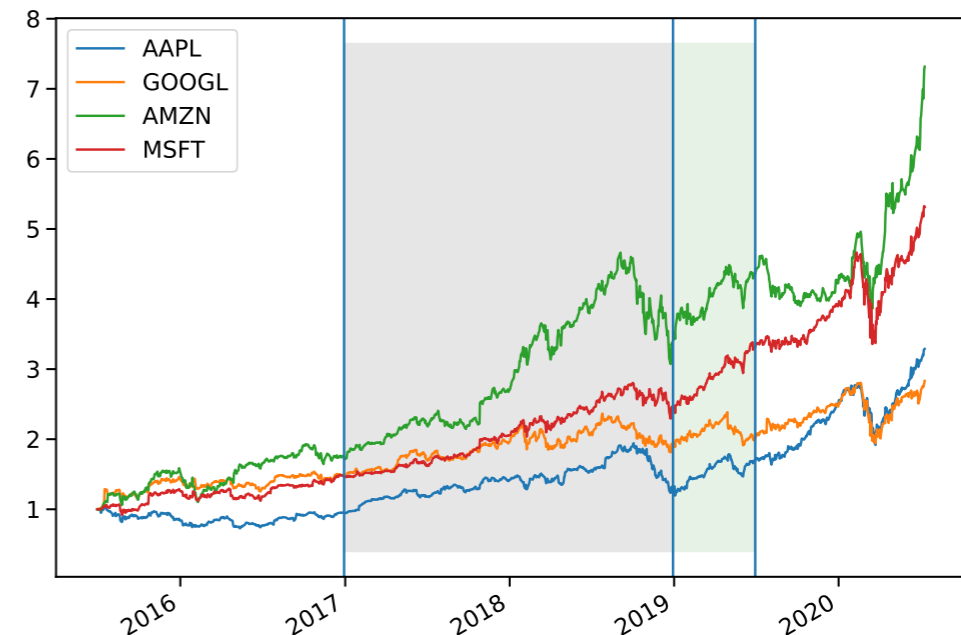
Portfolio Allocation

Given N stocks, how should I weight them to get an optimal portfolio?

Markowitz Portfolio Theory

$$w_{opt} = \min_w (w^T K w - q w^T \mu)$$

Learn weights on previous 2 years
Hold portfolio for next 6 months

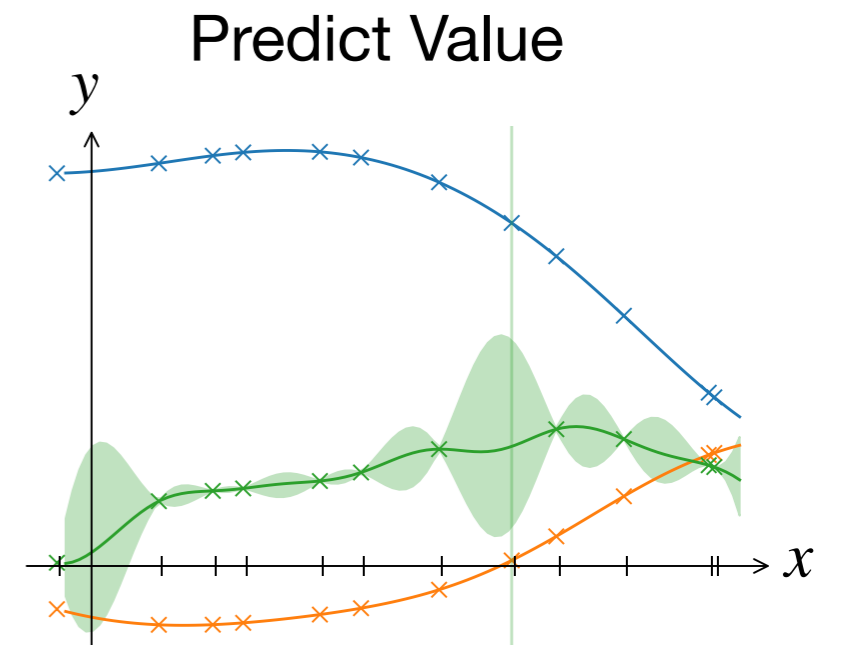
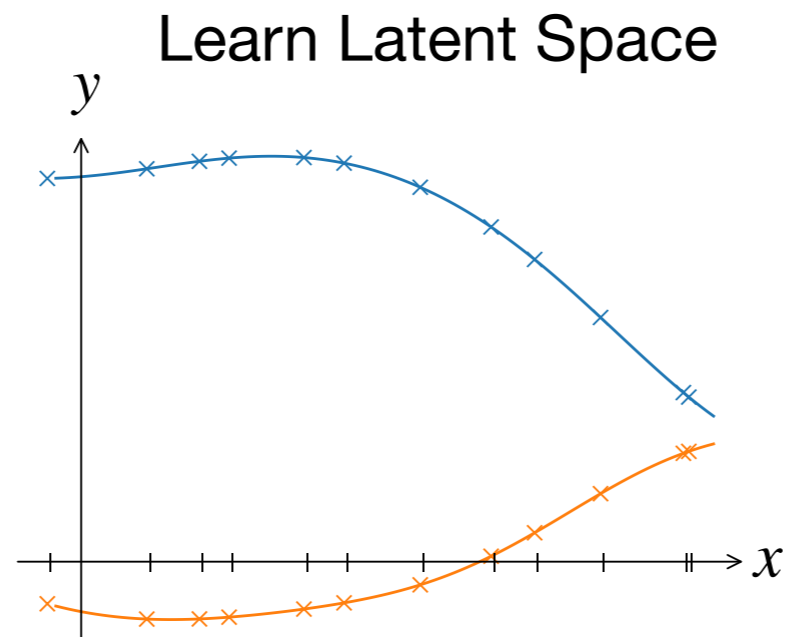


Backtesting on S&P500 from 2002 to 2018

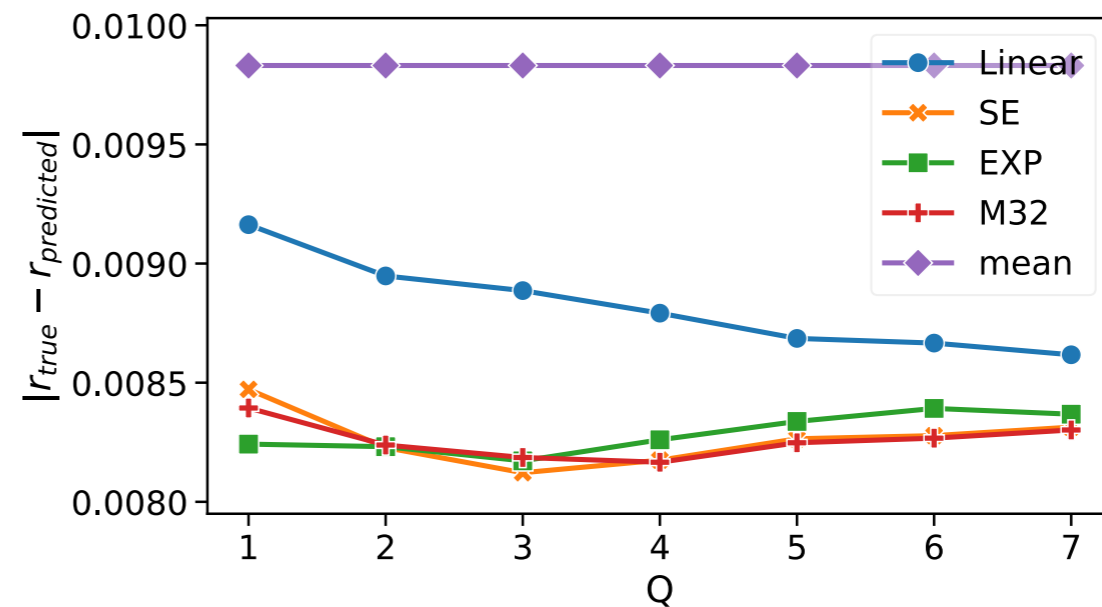
Model	Linear	SE	EXP	M32	Sample Cov	Ledoit Wolf	Eq. Weighted
Mean	0.142	0.151	0.155	0.158	0.149	0.148	0.182
Std	0.158	0.156	0.154	0.153	0.159	0.159	0.232
Sharpe ratio	0.901	0.969	1.008	1.029	0.934	0.931	0.786

Predict Missing Values

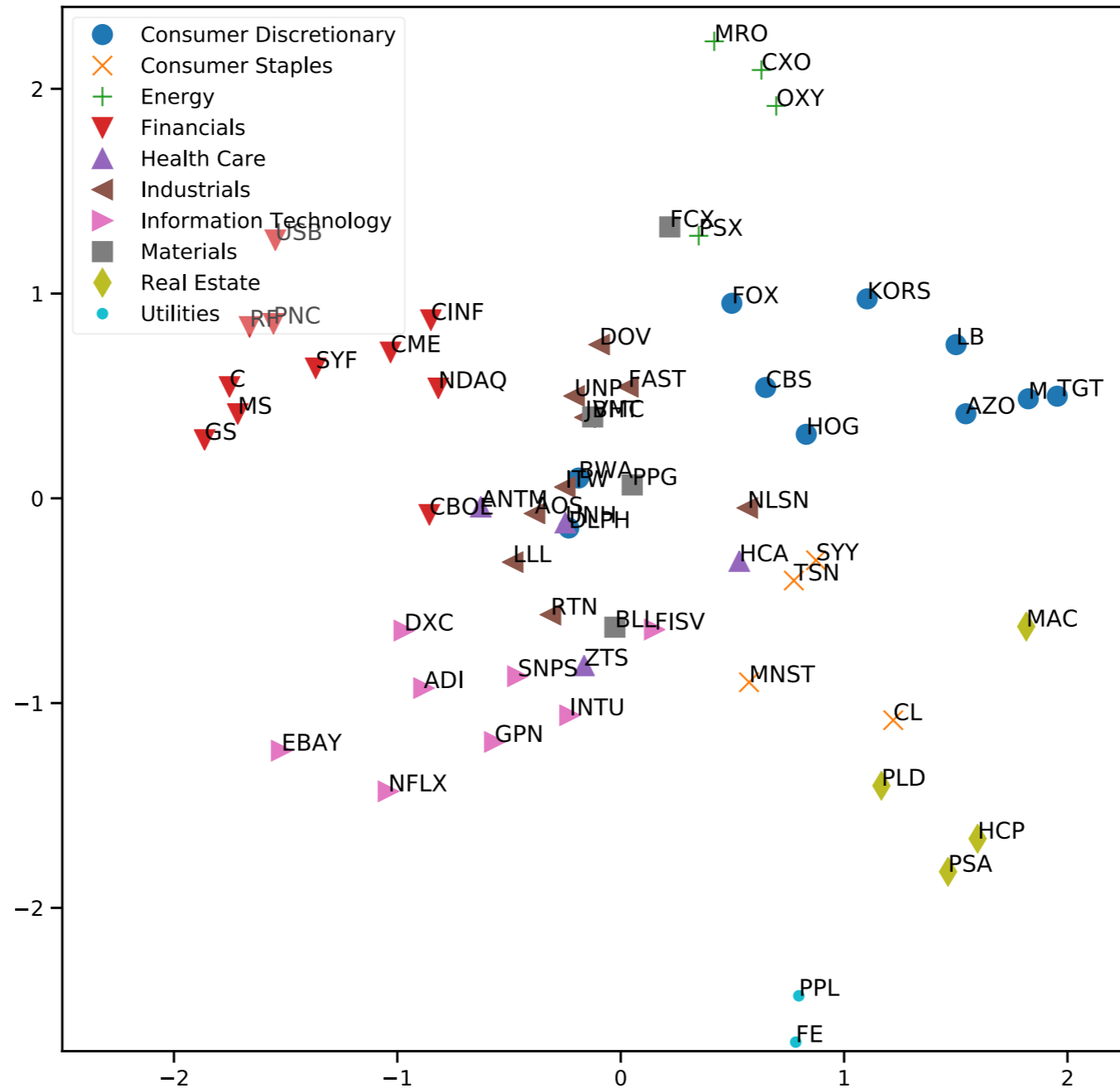
$$\begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & NaN \\ \dots & c_1 & c_2 & c_3 \\ d_1 & d_2 & d_3 \end{pmatrix}$$



Prediction of missing values for held out dataset

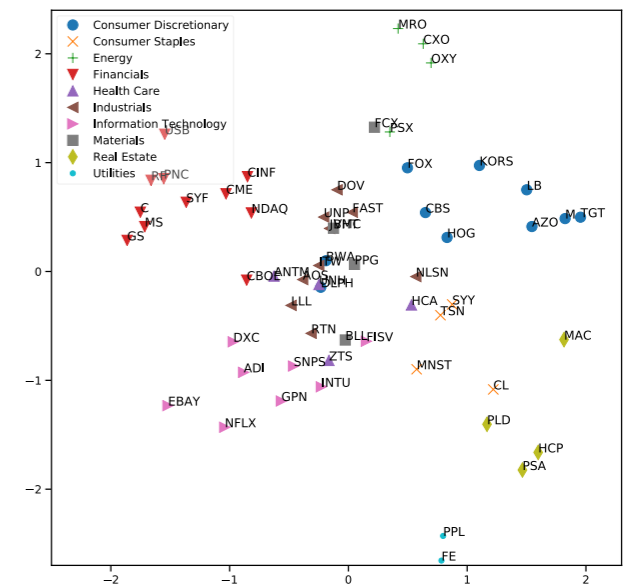
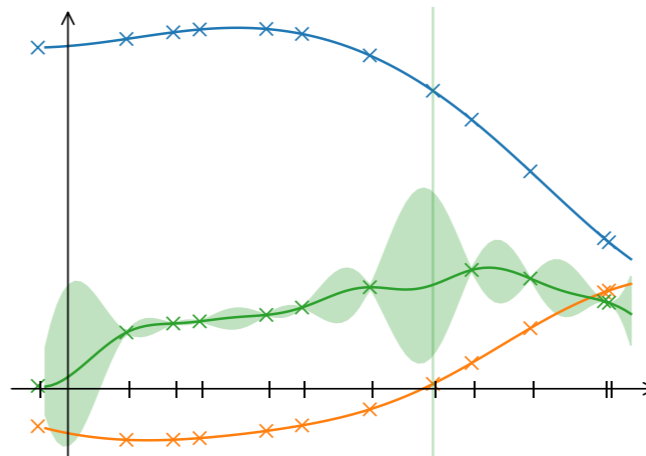
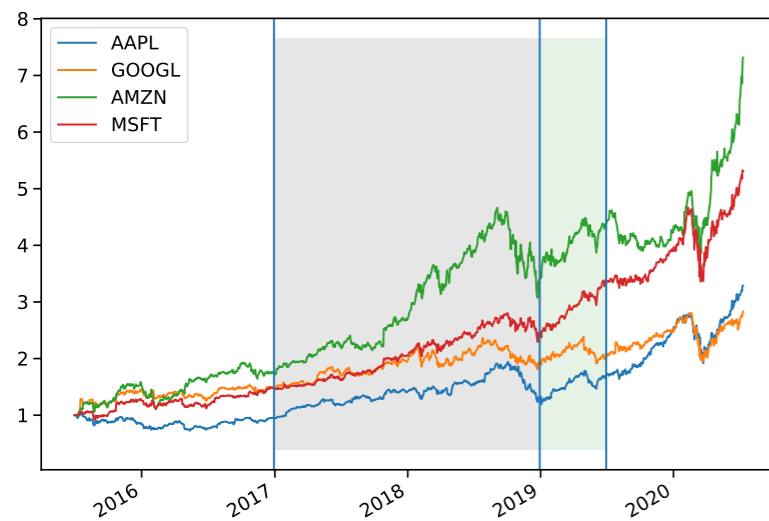


Visualization of Latent Space



Summary

- Use of Gaussian Processes in Finance
- Build Portfolio based on the Covariance between Stocks
- Better Predictor for Missing values
- Latent Space Structure Identification



Summary

- Use of Gaussian Processes in Finance
- Build Portfolio based on the Covariance between Stocks
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<https://github.com/RSNirwan/GPLVMsInFinance>

Applications of Gaussian Process Latent Variable Models in Finance

RS Nirwan, N Bertschinger - Proceedings of SAI Intelligent Systems Conference, 2019