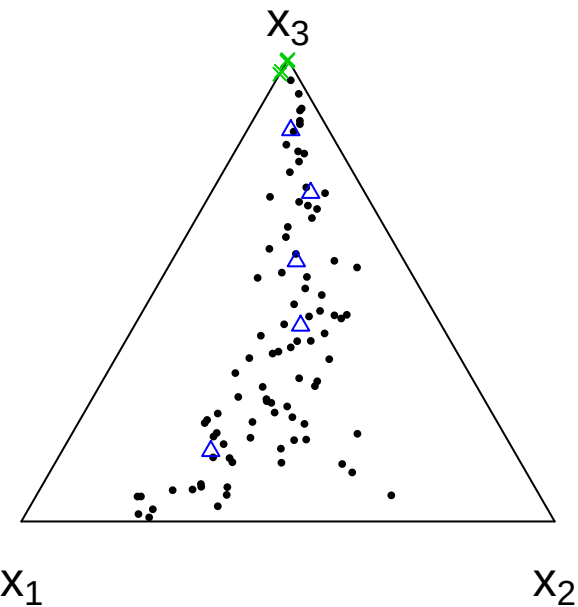
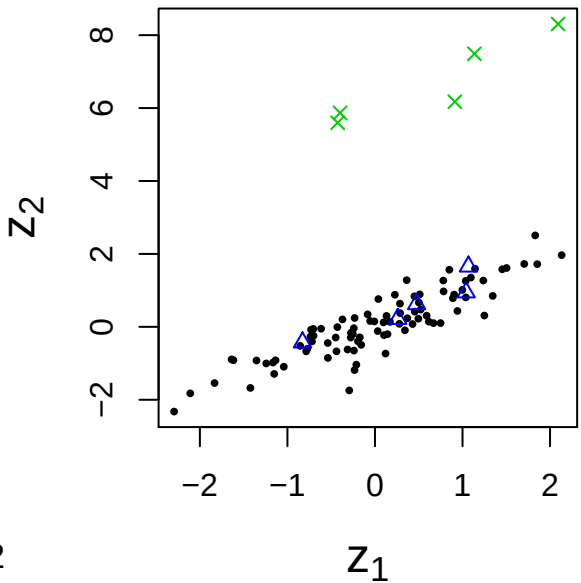

x_3
x_1
x_2


z_2
8
6
4
2
0
−2
−2
−1
0
1
2
z_1